## New design enhances ease of use.

High performance, compact rotary actuator offers space savings and high torque.

Rotary actuators vane type

## RAN <br> Series

Featuring an aluminum alloy body. Precision machining and special surface treatment of the inner surface, specially shaped seals, and bearings using oil impregnated metal, etc., result in a non-lubrication, longlife rotary actuator with high-torque and high-performance that is also compact and lightweight, with extremely little air leakage.

- The series is finely categorized according to the nominal torque. The range also includes units with compact sensor switches that increases its application flexibility and different possible devices you can design.



## Basic Model and Configuration


$\square$ RAN $\square 1,3,8,20$ are each available in swing angle specifications of $90^{\circ}, 100^{\circ}, 180^{\circ},\left(190^{\circ}\right)$, and $270^{\circ}$.
RAN $\square 50$ is available in swing angle specifications of $90^{\circ}, 100^{\circ}, 180^{\circ}, 190^{\circ}$, and $275^{\circ}$.
Note: Items in parentheses ( ) are made to order.

Relationship between Swing Angle and Keyseat Location

| $90^{\circ}$ Specification | $100^{\circ}$ Specification | $180^{\circ}$ Specification | $190^{\circ}$ Specification ${ }^{\text {Note }}$ | $270^{\circ}$ Specification | $275{ }^{\circ}$ Specification |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Starting point of swing: $45^{\circ}$ | Statring point of swing: $45^{\circ}$ (RAN50 is $\left.40^{\circ}\right)$ | Starting point of swing: $45^{\circ}$ | Starting point of swing: $45^{\circ}$ (RAN50 is $40^{\circ}$ ) | Starting point of swing: $45^{\circ}$ | Starting point of swing: $45^{\circ}$ |

Both the direct mounting and bracket mounting (for RAN $\square 50$ only) types are designed to ensure a high degree of precision in the parallelism to the mounting surface for the rod center or perpendicularity to the rod center.

RAN $\square \mathbf{1 , 3 , 8 , 2 0}$


Remark: RAN $\square$ 1, 3, $\mathbf{8}$ and $\mathbf{2 0}$ are direct mounting only.
RAN $\square 50$

| ■Nose mount (direct front mounting) | DFoot mount (using foot mounting brackets) |
| :---: | :---: |
|  |  |
| $\square$ Flange mount (using flange mounting bracket) |  |

## Symbol



## Specifications

| Item | RAN $\square \mathbf{1}$ | RAN $\square 3$ | RAN $\square 8$ | RAN $\square 20$ | RAN $\square 50$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Operation type | Double acting single vane type |  |  |  |  |
| Effective torque ${ }^{\text {Noter }}$ N.m [ft.lbf] | 0.118 [0.087] | 0.294 [0.217] | 0.785 [0.579] | 1.961 [1.446] | 5.197 [3.833] |
| Swing angle ${ }^{\text {Note2 }}$ <br> (Tolerance ${ }^{+3^{\circ}}$ ) | $90^{\circ}, 100^{\circ}, 180^{\circ},\left(190^{\circ}\right), 270^{\circ}$$\text { ( } 190^{\circ} \text { is made to order.) }$ |  |  |  | $\begin{gathered} 90^{\circ}, 100^{\circ}, 180^{\circ}, \\ 190^{\circ}, 275^{\circ} \end{gathered}$ |
| Media | Air |  |  |  |  |
| Port size | M5 $\times 0.8$ |  |  | M5 $\times 0.8$ | Rc1/8 |
| Rod diameter mm [in.] | 4 [0.157] | 5 [0.197] | 6 [0.236] | 8 [0.315] | 12 [0.472] |
| Operating pressure range MPa [psi.] | $\begin{aligned} & 0.25 \sim 0.7 \\ & {[36 \sim 102]} \end{aligned}$ | $0.2 \sim 0.7$ [29~102] |  |  |  |
| Proof pressure MPa [psi.] | 1.03 [149] |  |  |  |  |
| Operating temperature range ${ }^{\circ} \mathrm{C}\left[{ }^{\circ} \mathrm{F}\right]$ (Atmosphere and media) | $5 \sim 60$ [41~140] |  |  |  |  |
| Internal capacity Note3 $\mathrm{cm}^{3}$ [in.3] | $2.04[0.124](4.07[0.248)$ | $4.48[0.273][8.96[0.547])$ | $11.05[0.677][22.1[1.35])$ | $27.2[1.66][54.4[3.32])$ | $56[3.42]$ (75 [4.58]) |
| Allowable energy $J$ [in.lbf] | 0.0004 [0.0035] | 0.002 [0.018] | 0.005 [0.044] | 0.015 [0.133] | 0.06 [0.53] |
| Allowable radial load N [lbf] | 19.6 [4.41] | 39.6 [8.90] | 58.8 [13.2] | 294.2 [66.1] | 588.4 [132.3] |
| Allowable thrust load Note4 N [lbf] | 2.0 [0.45] | 3.9 [0.88] | 5.9 [1.33] | 29.4 [6.61] | 98.1 [22.1] |
| Lubrication | Not required |  |  |  |  |
| Cushion | None | Rubber bumper |  |  | None |
| Sensor switch Note5 | The sensor switch can be installed on type RANS $\square$. Applicable sensor switch: ZC130 $\square$, ZC153 $\square$, CS5T $\square$, CS11T $\square$ |  |  |  |  |

Notes: 1. Value when the air pressure is 0.5 MPa [73psi].
2. Angle tolerance is the value at the maximum swing angle for the specification. Note, however, that RAN1 is ${ }^{+4}$.
3. Values when swing angle is $90^{\circ}$. Values in parentheses ( ) are at the maximum swing angle for the specification.
4. Numerical values are reference values, not guaranteed values. For details, see p.1281.
5. For details of sensor switches, see p.1544.

Operation Principle


When air supplied from Port A pushes against the vane and generates torque, the vane rod rotates. Air in opposite side of the vane is exhausted from Port B.
Air supplied from Port B will generate torque in the opposite direction from the diagram shown above. Air in opposite side of the vane is exhausted from Port A.

## Mass



Calculation example: Mass of RANS1-90-2 (side-mounted) with 2 sensor switches (lead wire length A),
$50+60=110 \mathrm{~g}$ [3.880z.]
Remark: There are 2 types of sensor switch lead wire lengths.
A: 1000 mm [39in.], B: 3000 mm [118in.]

ORAN $\square 1$

-RAN $\square 3$


RAN $\square 8$


RAN $\square 20$


RAN $\square 50$


- RAN $\square 1$

- RAN $\square 3$


RAN $\square 8$

-RAN $\square 20$


- RAN $\square 50$

$1 \mathrm{~cm}^{3} /$ cycle $=0.0610 \mathrm{in} 3 /$ cycle
$1 \ell /$ cycle $=0.0353 \mathrm{ft}^{3} /$ cycle
$1 \mathrm{MPa}=145 \mathrm{psi}$.

Air consumption per cycle of the rotary actuator can be found by the following calculation formula.
$\mathrm{Q}=2 \times \mathrm{V} \times 10^{-3} \times\left(\frac{(\mathrm{P}+0.1013)}{0.1013}\right)$
Q : Air consumption per 1 cycle [ $\ell /$ cycle (ANR)]
V : Internal capacity ( $\mathrm{cm}^{3}$ )
P : Operating air pressure (MPa)
$Q^{\prime}=2 \times V^{\prime} \times \frac{1}{1728} \times\left(\frac{\left(P^{\prime}+14.696\right)}{14.696}\right)$
$\mathrm{Q}^{\prime}$ : Air consumption per 1 cycle [ ft .3/cycle (ANR)*]
$\mathrm{V}^{\prime}$ : Internal capacity (in.3)
$P^{\prime}$ : Operating air pressure (psi.)
※Refer to p. 54 for an explanation of ANR.

## RAN

Rotary Actuator Standard Type

## Order Codes

RAN1, 3, 8, 20


Inner Construction, Major Parts and Materials
RAN1, 3, 8, 20


| No. | Parts | Materials |
| :---: | :--- | :--- |
| (1) | Main body A | Aluminum alloy (anodized) |
| (2) | Main body B | Aluminum alloy (anodized) |
| (3) | Vane rod | (output shaft) |
|  | Vane rod (rotor) | (nitriding processing) |
|  | Pastic |  |
| (4) | Shoe seal | Synthetic rubber (NBR) |
| (5) | Shoe | Plastic |
| (6) | Sliding bearing | Oil impregnated sintered alloy |
| (7) | O-ring | Synthetic rubber (NBR) |

## RAN50



## Inner Construction, Major Parts and Materials

## RAN50



| No. | Parts | Materials |
| :---: | :--- | :--- |
| (1) | Main body A | Aluminum alloy (anodized) |
| (2) | Main body B | Aluminum alloy (anodized) |
| (3) | Vane rod | Alloy steel (nitididing processing) |
| (4) | Vane seal | Synthetic rubber (NBR) |
| (5) | Shoe | Plastic |
| (6) | Shoe seal | Synthetic rubber (NBR) |
| 77 | Sliding bearing | Oil impregnated sintered alloy |
| (8) | O-ring Note1 | Synthetic rubber |
| (9) | O-ring Note2 | (NBR) |
|  | Foot mounting bracket | Mild steel |
|  | Flange mounting bracket | Mild steel |

Notes: 1. P14 or equivalent: 2 pcs.
2. $\phi 62.5 \times \phi$ 2: 1 pc .

## Side mount (Direct side mounting)

RAN1- Swing angle -2


## Front mount (Direct front mounting)

RAN1- Swing angle -4

Side mount (Direct side mounting)
RAN3- Swing angle -2


RAN3-2


Front mount (Direct front mounting)
RAN3- Swing angle -4


## Side mount (Direct side mounting)

RAN8- Swing angle -2



Front mount (Direct front mounting)
RAN8- Swing angle -4


## Side mount (Direct side mounting)

RAN20- Swing angle -2


RAN20-2



Front mount (Direct front mounting)
RAN20- Swing angle -4



## Nose mount (Direct front mounting)

RAN50- Swing angle


Foot mount

## (Using foot mounting bracket)

RAN50-
Swing angle -1A

RAN50-1A


Flange mount
(Using flange mounting bracket)
RAN50- Swing angle -3A

RAN50-3A


Dimensions of the key and keyseat

※ The position of the keyseat in the drawings varies from the actual product. For the positional relationship with the swing angle, see p.1259. The key is included at shipping.

## SENSOR SWITCHES

Solid State Type, Reed Switch Type

Order Codes for Sensor Switches Only


For details of sensor switches, see p.1544.
A: 1000 mm [39in]
B: 3000 mm [118in]

## Sensor Switch Operating Range, Response Differential, and Maximum Sensing Location

Operating range: $\ell$
The angle the rotor travels in one direction, while the switch is in the ON position.

Response differential: C
The angle between the point where the rotor turns the switch ON and the point where the switch is turned OFF as the rotor travels in the opposite direction.


RANS1, 3, 8, 20

| Sensor switch model | Solid state type | Reed switch type |
| :--- | :---: | :---: |
|  | ZC130 $\square, \mathbf{Z C 1 5 3} \square$ | CS5T $\square, \mathbf{C S 1 1 T} \square$ |
| Operating range: $\ell$ | About $70^{\circ}$ | About $36^{\circ}$ |
| Response differential: C | About $1.5^{\circ}$ | About $6^{\circ}$ |
| Operating position | About $35^{\circ}$ | About $18^{\circ}$ |


| RANS50 |  |  |
| :--- | :---: | :---: |
| Sensor switch model | Solid state type | Reed switch type |
|  | ZC130 $\square, \mathbf{Z C 1 5 3} \square$ | CS5T $\square$, CS11T $\square$ |
| Operating range: $\ell$ | About $29^{\circ}$ | About $16^{\circ}$ |
| Response differential: C | About $2^{\circ}$ | About $3^{\circ}$ |
| Operating position | About $14.5^{\circ}$ | About $8^{\circ}$ |

## Moving and Adjusting of Sensor Switch

Since the maximum sensing location of the sensor switch will vary depending on the model, use the guidelines below for moving and adjusting the sensor switch during mounting.
The RANS with sensor switches has been adjusted at the factory before shipping.

- Use a cover to temporarily secure the sensor switch, and set the magnet directly underneath the sensor switch.
- Move the sensor switch from the rear portion of the cover in the direction of the body, and confirm the point where it turns ON (LED turns ON with indicator lamp type). Then, move it 1 notch further (about $1 \mathrm{~mm}[0.04 \mathrm{in}]$ ) for the solid state type ZC130 and ZC153 or 2 notches (about 2 mm [0.08in]) for the reed switch type CS5T and CS11T toward the RANS body, and tighten the mounting screw to secure it in place.

When installing the sensor switch, always mount so that the model marking surface faces upward.
Mounting with the model marking on the bottom or side surfaces could result in improper operation.


## Sensor switches

## Parts in sensor cover

RANS1, 3, 8, 20


## How to detach the end cover

RANS1, 3, 8, 20
Push up the end cover to remove, as shown in the diagram.


## RANS50

Operation is easily accomplished simply by inserting a flat blade screwdriver of appropriate size into the slot and pry it away lightly, as shown in the diagram.



1. RANS sensors are pre-adjusted to the swing angles at shipping from the factory. Do not attempt any unnecessary disassembly or removal.
If readjustment is required, see "Arrangement of swing angle and magnet holder" on the next page.
2. Two magnet holders are mounted even with orders that do not have any RANS sensors or have just 1 unit.

## Sensor operation beyond the set angle

Loosen the magnet holder's hexagon socket head bolt, as shown in the diagram, and move the holder to the required angle for operation.


Note: If the holder has been removed, always mount it so that the magnet end surface with the [S] marking faces toward the RAN body. Mounting in the reverse direction could result in failure of the sensor switch to operate.

RANS1, 3, 8, 20
For ZC130 $\square$ and ZC153

$90^{\circ}$


For CS5T $\square$ and CS11T $\square$

$90^{\circ}$

$180^{\circ}$

$90^{\circ}$

$180^{\circ}$


RANS50

Relationship between swing angle and keyseat location

| $90^{\circ}$ Specification | $100^{\circ}$ Specification | $180^{\circ}$ Specification | $190^{\circ}$ Specification ${ }^{\text {Note }}$ | $270^{\circ}$ Specification | $275{ }^{\circ}$ Specification |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Starting point of swing: $45^{\circ}$ | Starting point of swing: $45^{\circ}$ (RAN50 is $40^{\circ}$ ) | Starting point of swing: $45^{\circ}$ | Starting point of swing: $45^{\circ}$ (RAN50 is $\left.40^{\circ}\right)$ | Starting point of swing: $45^{\circ}$ | Starting point of swing: $45^{\circ}$ |



## Selection

1. Allow plenty of margin for output (torque). Set the required torque at $80 \%$ or less (50\% or less for fluctuating loads) of the effective torque.
The inertia load becomes larger when the load mass is large, or during high operating speeds, it may exceed the rotary actuator's allowable kinetic energy. In this case, install a shock absorber to prevent the rotary actuator from inertia force being directly applied.
2. The positional relationship between the swing angle and the keyseat is as shown on p.1259. Even though tolerance of the swing angle is within the range of ${ }_{0}^{+3}$ to the specification angles, install an external stopper, etc., to maintain accurate positioning.
3. For the swing time of the rotary actuator (the time it takes to reach the end of swing stroke from starting movement), see the table below as a guideline.

| Model swing ange | $90^{\circ}, 100^{\circ}$ | $180^{\circ}, 190^{\circ}$ | 270 ${ }^{\text {Note }}$ |
| :---: | :---: | :---: | :---: |
| RAN1 | $0.03 \sim 0.3$ | 0.06~0.6 | $0.08 \sim 0.8$ |
| RAN3 | $0.04 \sim 0.4$ | $0.08 \sim 0.8$ | $0.1 \sim 1.0$ |
| RAN8 | $0.05 \sim 0.5$ | $0.1 \sim 1.0$ | 0.15~1.5 |
| RAN20 | $0.06 \sim 0.6$ | 0.12~1.2 | $0.2 \sim 2.0$ |
| RAN50 | 0.08~1.0 | 0.16~1.8 | 0.2~3.0 |

Remark: Conditions are air pressure at 0.5 MPa [73psi.] and no load.
Note : RAN50 is $275^{\circ}$ specification.
Caution: Excessively high kinetic energy could damage the rod of the rotary actuator. Always use within the allowable energy.


## Mounting

## Precautions concerning the loading direction

1. Since thrust loads applied in the axial direction on the vane type rotary actuator can result in improper operation or reductions in durability, take adequate precautions for mounting and operating the product.
The allowable thrust load listed in this catalog is a reference value only, and not a guaranteed value.
2. While radial loads perpendicular to the rod can be considered to be static loads within the specification values (see p.1261), dynamic loads are limited to loads within the allowable energy.
Moreover, since eccentric loads perpendicular to the rod can result in improper friction or damage to the sliding bearings, use flexible couplings for connections as much as possible.
3. During mounting, set loads or select fittings to avoid applying stresses or loads to the body.

$\bigcirc$



## General precautions

1. Always thoroughly blow off (use compressed air) the tubing before piping. Entering metal chips, sealing tape, rust, etc., generated during piping work could result in air leaks or other defective operation.
2. Use air for the media. For the use of any other media, consult us.
3. The product cannot be used when the media or ambient atmosphere contains any of the substances listed below.
Organic solvents, phosphate ester type hydraulic oil, sulphur dioxide, chlorine gas, or acids, etc.
4. If using in locations subject to dripping water, dripping oil, etc., or to large amounts of dust, use a cover to protect the unit.
