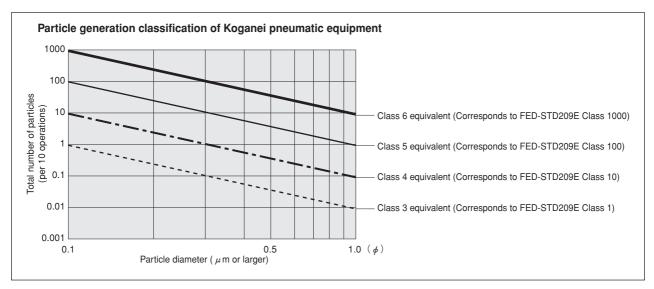


Koganei Clean System products provide complete support for the maintenance of a clean environment inside the cleanroom.

Koganei Clean System products meet the needs of the ultra-clean production environment. In everything from actuators and valves to air preparation and auxiliary equipment, anti-corrosion materials processing and other Koganei-developed design concepts serve to prevent particle contamination within the cleanroom. These perfectly designed mechanisms, which resolve even the slightest leaks to the outside during operations, have already won a high level of reliability.

Koganei Cleanliness

There is currently no standard in JIS or elsewhere for methods of evaluating cleanliness for pneumatic equipment in the cleanroom specifications. Therefore, to measure the effects of cleanroom contamination by pneumatic equipment, Koganei has decided to use "number of particles generated per 10 operations," rather than particle density. Koganei has also developed classifications for application classes in cleanroom, based on JIS and other upper limit density tables, and on the company's own experience.



Remarks: 1. In the above table, product performance in terms of the number of particles generated per 10 operations is expressed as the upper limit of particles corresponding to the equivalent JIS or ISO class.

- 2. In the above table, values in the JIS, ISO, and FED-STD upper limit density tables are calculated as upper density per liter.
- 3. The classes shown are clean levels as classified in JIS and ISO.

From the above definitions, the Koganei clean level classes can be viewed as the level of average contamination per liter of surrounding air over a period of 10 operations in cleanroom. Air ventilation in cleanrooms is usually faster than 1 cycle per minute, and clean volumetric capacity is usually larger than 1 liter, which should provide a sufficient safety margin in practice.

Caution: The above conclusions are based on an ideal situation in which air ventilation is being implemented. For specific cases where air ventilation is not ensured, caution is needed since the clean classes cannot be maintained.

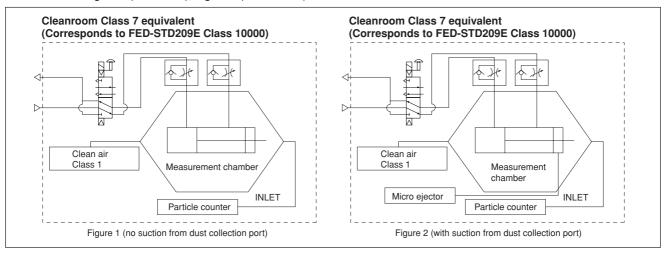
The clean system diagrams shown here are for Class 5 equivalent products. For Class 4 or Class 3 equivalent products, consult us.

Koganei has therefore specified its in-house measurement methods, to conduct evaluations on the cleanroom rating.

The number of particles of the Air Cylinder Cleanroom Specification is measured as shown in the method below.

1. Measurement conditions

1-1 Test circuit: Figure 1 (no suction), Figure 2 (with suction)



1-2 Operating conditions of tested cylinder

Operating frequency: 1Hz

Average speed: 500mm/s [20in./sec.] Applied pressure: 0.5MPa [73psi.]

Suction condition: Microejector ME05, Primary side: 0.5MPa [73psi.] applied, Tube: ∮6 [0.236in.]

Mounting direction: Vertical Chamber volume: 8.3 ℓ [0.293ft.*]

2. Particle counter

Manufacturer/model: RION/KM20 Suction flow rate: 28.3 ℓ /min [1ft:/min.]

Particle diameter: 0.1 μ m, 0.2 μ m, 0.3 μ m, 0.5 μ m, 0.7 μ m, 1.0 μ m

3. Measurement method

3-1 Confirmation of number of particles in the measurement system

Under the conditions in the above 1 and 2, using a particle counter to measure the sample for 9 minutes without operating the measurement sample, and confirmed the measured number of particle is 1 piece or less.

3-2 Measurement under operation

Under the conditions in the above1 and 2, operating the measurement sample for 36 minutes, and measured the total values in the latter half of 18 minutes test.

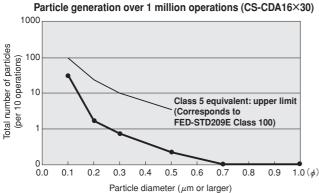
3-3 Reconfirmation

Performed the measurement in 3-1 again, to reconfirm the number of particles in the measurement system.

4. Measurement results

Cleanroom specification

Jig Cylinder (no suction from dust collection port)



Cleanroom specification

Slim Cylinder (with suction from dust collection port)

Particle generation over 1 million operations (CS-DA20×100) 1000 fotal number of particles (per 10 operations) Class 5 equivalent: upper limit (Corresponds to FED-STD209E Class 100) 0.0 0.1 0.2 0.3 0.4 0.5 0.6 0.7 8.0 0.9 $1.0(\phi)$ Particle diameter (µm or larger)

Safety Precautions

Always read these precautions carefully before use.

For "safety precautions" listed in the Clean System Product Drawings, see the materials below.

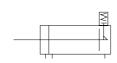
- \bullet For actuators, see "Safety Precautions" on p. 45 of the Actuators General Catalog .
- For valves, see "Safety Precautions" on p. 31 of the Valves General Catalog.
- For air treatment and auxiliary equipment, see "Safety Precautions" on p.31 of the General Catalog of Air Treatment, Auxiliary, Vacuum.



Head Side End Keep Double Acting Type

Symbols

KOGANEI





Specifications

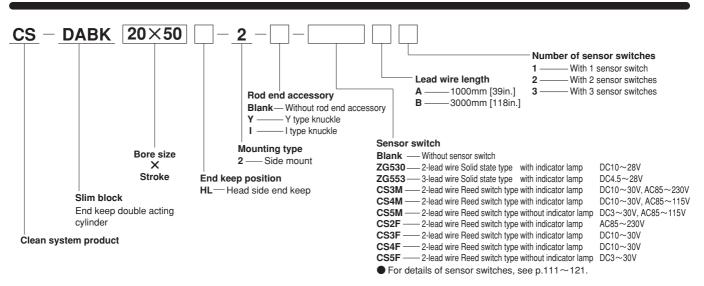
D	00 [0 =0=1	0	00.51.0003	40.54.0003								
Item Bore size mm [in.]	20 [0.787]	25 [0.984]	32 [1.260]	40 [1.575]								
Operating type]	Double acting type, with head s	ide stroke end keep mechanisn	n								
Media		А	ir									
Mounting type		Side ı	mount									
Operating pressure range MPa [psi.]		0.1~0.9 [15~131]										
Proof pressure MPa [psi.]	1.32 [191]											
Operating temperature range °C [°F]		0~60[3	32~140]									
Operating speed range mm/s [in./sec.]		50~300 [2.0~11.8]									
Cushion		Fixed type (Ru	ubber bumper)									
Lubrication		Not re	quired									
Maximum holding force (at end keep) N [lbf.]	194.2 [43.66]	303 [68.11]	496.2 [111.5]	775.7 [174.4]								
Backlash (at end keep) mm [in.]	1.4 [0.05	55] MAX.	1.6 [0.063] MAX.									
Port size Rc		1,	/8									

Bore Size and Stroke

			mm [in.]
Bore size	Standard strokes	Maximum stroke	Maximum available stroke
20 [0.787]	25 50 75 100 125 150	150	
25 [0.984]	25 50 75 100 125 150 200	200	500
32 [1.260]	25 50 75 100 125 150 200	200	300
40 [1.575]	25 50 75 100 125 150 200 250 300	300	

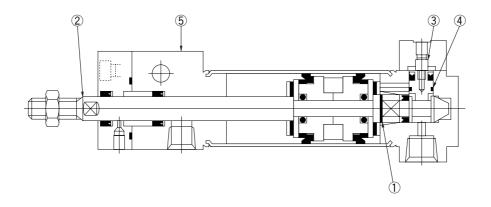
Remarks: 1. Stroke tolerance ${}^{+1}_{0}$ [${}^{+0.039}_{0}$]

Order Codes



● For the order codes of additional parts, see p. 64.

^{2.} For non-standard strokes, consult us.



Major Parts and Materials

Parts	Bore size mm	20, 25	32, 40						
1	Piston rod A	Steel (chro	me plated)						
2	Piston rod B	Stainless steel							
3	Spring	Stainless steel	Piano wire						
4	Lock piston	Stainless steel							
(5)	Lock cover	Aluminum (anodized)							
	Y type knuckle, I type knuckle	Mild steel (n	ickel plated)						

Other than the items listed above, it is the same as for the standard Slim Cylinder.

Seals

Parts	Rod seal	Lock piston seal	Lock cover gasket
Bore mm Quantity	1	1	1
20	GYH-9	MYN-5	_
25	GYH-11	MYN-5	_
32	_	MYN-10A	S18
40	_	MYN10-A	S18

Other than the items listed above, it is the same as for the standard Slim Cylinder.

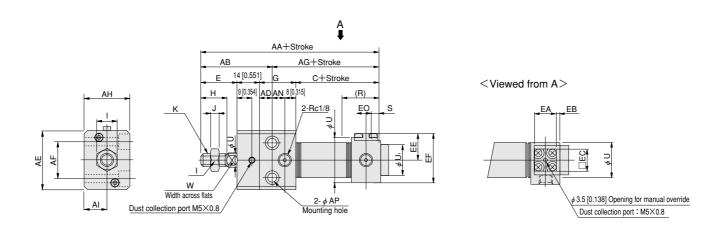
Mass

				g [oz.]					
	Zero stroke mass	Additional mass for each	Mass of knuckle						
Bore size mm [in.]	LII · Hood side and keep		Y type knuckle	I type knuckle					
20 [0.787]	210 [7.41]	0.8 [0.028]	41 [1.45]	36 [1.27]					
25 [0.984]	310 [10.93]	1.1 [0.039]	75 [0.05]	70 [0 47]					
32 [1.260]	500 [17.64]	1.5 [0.053]	75 [2.65]	70 [2.47]					
40 [1.575]	900 [31.75]	2.4 [0.085]	120 [4.23]	132 [4.66]					

Calculation example: For head side end keep side mount type of 32mm bore size and 100mm stroke, 500+(1.5×100)=650g [22.93 oz.]

-HL Dimensions of Head Side End Keep, Side Mounting Type $_{\text{mm}}$ [in.]

$\Phi \phi 20 \sim \phi 40$



• The drawings for sizes ϕ 32 and ϕ 40 (The outward shape of the size ϕ 20 and ϕ 25 head covers is larger than the block portion.)

Bore Code	С	Е	G	Н	I	J	K	R	S	U	U ₁	V	W
20 [0.787]	60 [2.362]	23 [0.906]	28 [1.102]	15 [0.591]	12 [0.472]	5 [0.197]	M8×1	16 [0.630]	6 [0.236]	29 [1.142]	20 [0.787]	8 [0.315]	6 [0.236]
25 [0.984]	60 [2.362]	26 [1.024]	30 [1.181]	18 [0.709]	14 [0.551]	6 [0.236]	M10×1.25	16 [0.630]	6 [0.236]	35 [1.378]	22 [0.866]	10 [0.394]	8 [0.315]
32 [1.260]	72 [2.835]	31 [1.220]	36 [1.417]	23 [0.906]	14 [0.551]	6 [0.236]	M10×1.25	26 [1.024]	1 [0.039]	35 [1.378]	27 [1.063]	12 [0.472]	10 [0.394]
40 [1.575]	79 [3.110]	31 [1.220]	44 [1.732]	23 [0.906]	19 [0.748]	8 [0.315]	M14×1.5	32 [1.260]	1 [0.039]	41.6 [1.638]	33 [1.299]	16 [0.630]	14 [0.551]

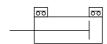
Bore Code	AA	AB	AD	AE	AF	AG	AH	Al	AN	AP		EB	EC	EE	EF	EO
20 [0.787]	131 [5.157]	48 [1.890]	11 [0.433]	38 [1.496]	22 [0.866]	83 [3.268]	28 [1.102]	14 [0.551]	9 [0.354]	φ6.6 [0.260] Counterbore φ11 [0.433] Depth 6.5 [0.256]		_	16 [0.630]	24 [0.945]	38.5 [1.516]	8 [0.315]
25 [0.984]	136 [5.354]	52 [2.047]	12 [0.472]	42 [1.654]	26 [1.024]	84 [3.307]	30 [1.181]	15 [0.591]	10 [0.394]	φ6.6 [0.260] Counterbore φ11 [0.433] Depth 6.5 [0.256]		_	16 [0.630]	25 [0.984]	42.5 [1.673]	8 [0.315]
32 [1.260]	154 [6.063]	59 [2.323]	14 [0.551]	54 [2.126]	34 [1.339]	95 [3.740]	36 [1.417]	18 [0.709]	14 [0.551]	φ 9 [0.354] Counterbore φ 14 [0.551] Depth 8.6 [0.339]		2 [0.079]	25 [0.984]	30 [1.181]	(40.5) ([1.594])	14 [0.551]
40 [1.575]	169 [6.654]	62 [2.441]	17 [0.669]	68 [2.677]	46 [1.811]	107 [4.213]	44 [1.732]	22 [0.866]	19 [0.748]	φ 11 [0.433] Counterbore φ 17.5 [0.689] Depth 10.8 [0.425]	24 [0.945]	4 [0.157]	25 [0.984]	32.5 [1.280]	(46) ([1.811])	16 [0.630]

SLIM CYLINDERS

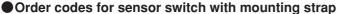
Sensor Switches

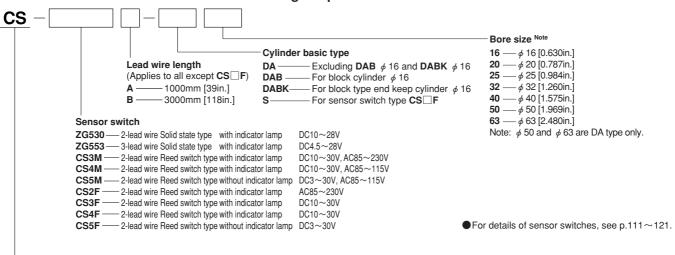
Since a magnet comes standard in the Slim cylinders series, mounting a sensor switch will enable use in sensor switch applications.

Symbol



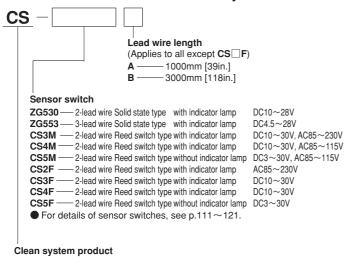
Order Codes



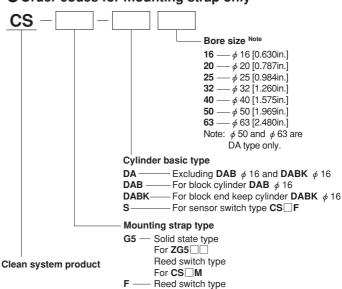


Clean system product

Order codes for sensor switch only



Order codes for mounting strap only



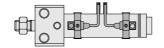
For **CS** \square **F**

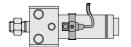
Minimum Cylinder Strokes When Using Sensor Switches

			·	mm [in.]			
Sensor switch	Bore size	2 pcs. n	nounting	1 pc. mounting			
model	Dole Size	In-line	In staggered positions	1 pc. mounting			
ZG530	16 [0.630]	20 [0.787]	10 [0.394]	10 [0.394]			
ZG553	20~63 [0.787~2.480]	20 [0.787]	10 [0.394]	10 [0.394]			
CS□M	16~63 [0.630~2.480]	20 [0.787]	15 [0.591]	15 [0.591]			
CS□F	20~63 [0.787~2.480]	40 [1.575]	21 [0.827]	15 [0.591]			

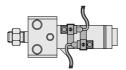
■Two pieces mounting One piece mounting

When mounted in-line





When mounted in staggered positions



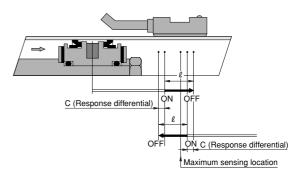
Sensor Switch Operating Range, Response Differential, and Maximum Sensing Location

lacktriangle Operating range : ℓ

The distance the piston travels in one direction, while the switch is in the ON position.

Response differential : C

The distance between the point where the piston turns the switch ON and the point where the switch is turned OFF as the piston travels in the opposite direction.



mm	lın	

Item	Bore size	16 [0.630]	20 [0.787]	25 [0.984]	32 [1.260]	40 [1.575]	50 [1.969]	63 [2.480]
	ZG530	2.5~4.1 [0.098~0.161]	2.5~4.2 [0.098~0.165]	2.6~4.3 [0.102~0.169]	3.0~4.8 [0.118~0.189]	3.1~5.0 [0.122~0.197]	3.3~5.4 [0.130~0.213]	3.5~5.7 [0.138~0.224]
Operating range : ℓ	CS M	6.7~7 [0.264~0.276]	7~8.5 [0.276~0.335]		8~9 [0.315~0.354]	•		·
	CS□F	_	7~8.5 [0.276~0.335]	8.5~10 [0.335~0.394]	9~10.5 [0.354~0.413]	10.5~12 [0.413~0.472]	9~10 [0.354~0.394]	9~10.5 [0.354~0.413]
	ZG530	0.7 [0.028] or less	0.7 [0.028] or less	0.8 [0.032] or less	0.7 [0.028] or less	0.8 [0.032] or less	0.8 [0.032] or less	0.8 [0.032] or less
Response differential : C	ZG533	0.7 [0.028] or less	0.7 [0.028] or less	0.8 [0.032] or less	0.7 [0.028] or less	0.8 [0.032] or less	0.8 [0.032] or less	0.8 [0.032] or less
nesponse differential . C	CS□M	1 [0.039] or less	1.2 [0.047] or less	1.2 [0.047] or less				
	CS□F	_	1.5 [0.059] or less	2 [0.079] or less	1.5 [0.059] or less			
Maximum agains	ZG530, ZG553 Note 1	11 [0.433]	11 [0.433]	11 [0.433]	11 [0.433]	11 [0.433]	11 [0.433]	11 [0.433]
location	CS M Note 1	11 [0.433]	11 [0.433]	11 [0.433]	11 [0.433]	11 [0.433]	11 [0.433]	11 [0.433]
	CS F Note 2	_	16 [0.630]	16 [0.630]	16 [0.630]	16 [0.630]	16 [0.630]	16 [0.630]

Remark : Figures in the table above are reference values.

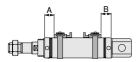
Notes: 1. Figures are from the end surface that is opposite to the lead wires.

2. Figures are from the end surface of the connector side.

Mounting Location of End of Stroke Detection Sensor Switch

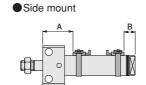
When the sensor switch is mounted in the location shown in the diagram below (figures in the table are reference values), the magnet comes to the maximum sensing location of the sensor switch at the end of the stroke.

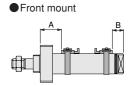
Double acting cylinder



							mm [in.]				
Sensor	Bore size	Double acting cylinder									
switch model	Code	20	32	32	40	50	63				
ZG530□ ZG553□	Α	37 [1.456]	37 [1.456]	37 [1.456]	38.5 [1.516]	45 [1.772]	45 [1.772]				
	В	27 [1.063]	27 [1.063]	27 [1.063]	27 [1.063]	36 [1.417]	36 [1.417]				
CS□M	Α	37 [1.456]	37 [1.456]	37 [1.456]	38.5 [1.516]	45 [1.772]	45 [1.772]				
OS_IM	В	27 [1.063]	27 [1.063]	27 [1.063]	27 [1.063]	36 [1.417]	36 [1.417]				
CS□F	Α	32 [1.260]	32 [1.260]	32 [1.260]	32 [1.260]	41 [1.614]	41 [1.614]				
	В	22 [0.866]	22 [0.866]	22 [0.866]	22 [0.866]	32 [1.260]	32 [1.260]				

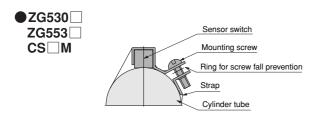
Block cylinder



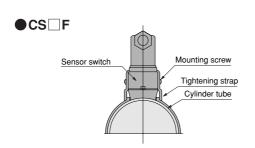


														mm	[in.]
Mount	ing type	Side mount									Fro	nt m	ount		
Bore	e size	16	20	25	32	40	50	63	16	20	25	32	40	50	63
ZG530	A Rod side	42 [1.654]	53 [2.087]	55 [2.165]	61 [2.402]	71 [2.795]	81 [3.189]	81 [3.189]	33 [1.299]	37 [1.457]	37 [1.457]	37 [1.457]	39 [1.535]	47 [1.850]	47 [1.850]
ZG553	B Rod side	16 [0.630]	20 [0.787]	20 [0.787]	21 [0.827]	25 [0.984]	45 [1.772]	45 [1.772]	16 [0.630]	20 [0.787]	20 [0.787]	21 [0.827]	25 [0.984]	45 [1.772]	45 [1.772]
00 TM	A Rod side	42 [1.654]	53 [2.087]	55 [2.165]	61 [2.402]	71 [2.795]	80 [3.150]	80 [3.150]	33 [1.299]	37 [1.457]	37 [1.457]	37 [1.457]	39 [1.535]	46 [1.811]	46 [1.811]
CS□M	B Rod side	16 [0.630]	20 [0.787]	20 [0.787]	21 [0.827]	25 [0.984]	44 [1.732]	44 [1.732]	16 [0.630]	20 [0.787]	20 [0.787]	21 [0.827]	25 [0.984]	44 [1.732]	44 [1.732]
CS□F	A Rod side	_	50 [1.969]	52 [2.047]	58 [2.283]	66 [2.598]	78 [3.071]	78 [3.071]	_	34 [1.339]	34 [1.339]	34 [1.339]	34 [1.339]	44 [1.732]	44 [1.732]
CSUF	B Rod side	_	17 [0.669]	17 [0.669]	18 [0.709]	20 [0.787]	42 [1.654]	42 [1.654]	_	17 [0.669]	17 [0.669]	18 [0.709]	22 [0.866]	42 [1.654]	42 [1.654]

Moving Sensor Switch



- Loosening the mounting screw allows the sensor switch to be moved freely along with the strap in the axial and circumferential direction. The sensor switch alone cannot be moved.
- To remove the sensor switch from the strap, first detach the strap from the cylinder tube and then remove the sensor switch from the strap.
- Tighten the mounting screw with a tightening torque of 49N·cm [4.3in·lbf] or less.



- Loosening the mounting screw allows the sensor switch to be moved freely in the axial and circumferential direction.
- Slightly loosening the mounting screw allows fine adjustment of the lead switch only, up to 5mm [0.197in.] in the axial direction.
 Tighten the mounting screw with a tightening torque of 68.6N·cm [6.1in·lbf] or less.

Dimensions of Sensor Switch mm [in.]

